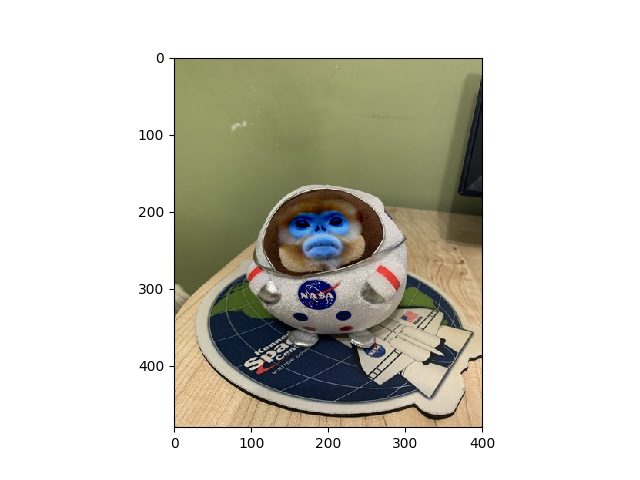
Seamless Cloning

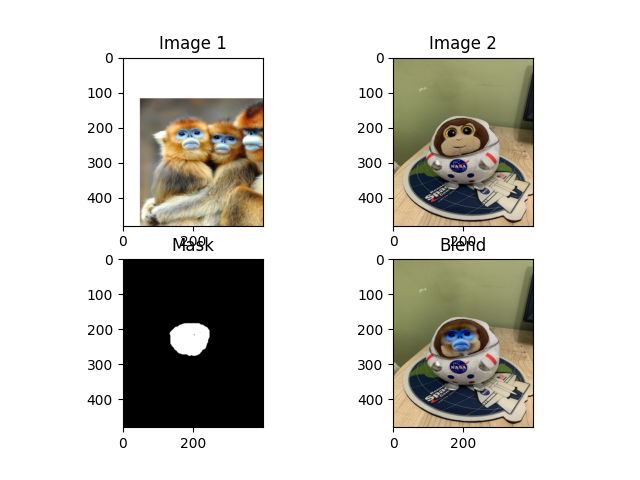
Tamer Ghattas | Computational Photography | 18.5.2021

# Part A

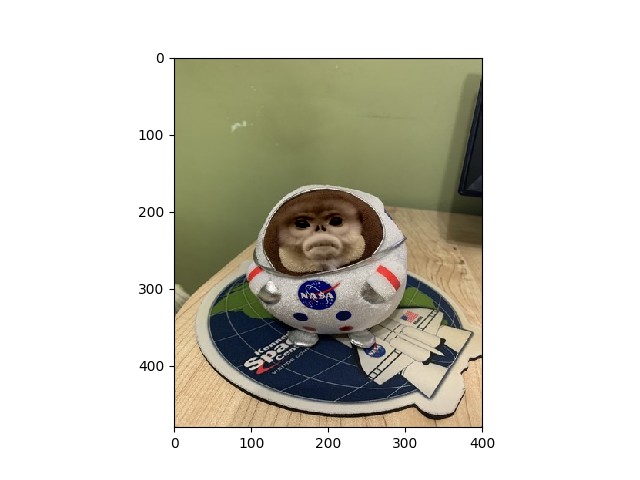
I’ve followed the paper in solving the equation #4:  
 over Ω with =

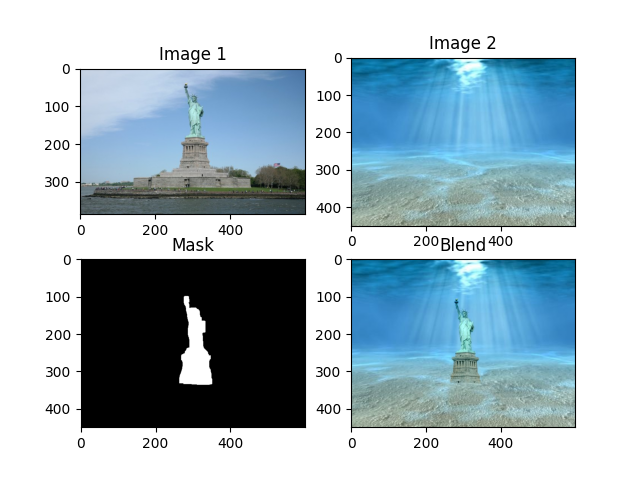
In the implementation I’ve used a binary mask as Omega and have built a linear equation where for each pixel, a variable in the equation system, and set equation inside the mask based on Poisson discrete matrix while set outside the mask as the identity matrix. Whereas on the right hand side of the equation, is a vector having a pixel inside the mask the value of operating div g = div “source” and target value for those outside the mask.

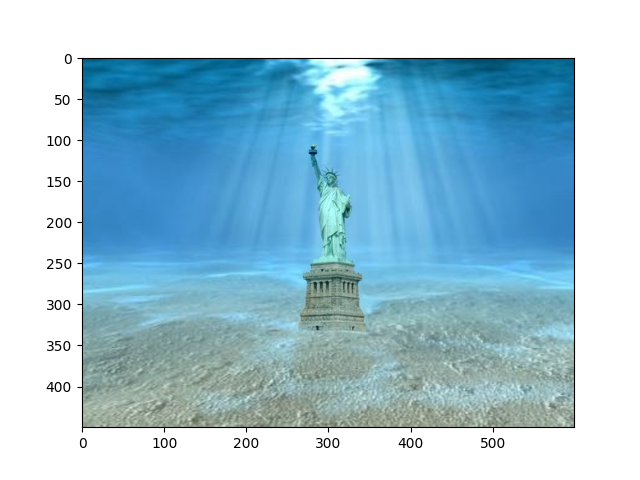
Results: 



Since there has been darkening to the center of the source image monkey face color, I’ve also tried using the source as monochromatic and got:



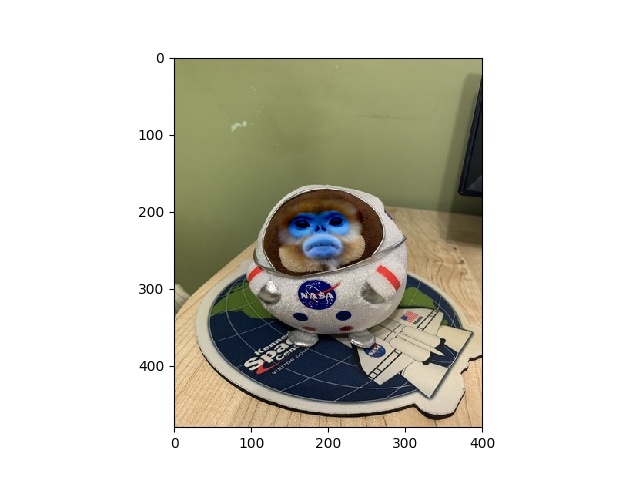
Additional example:  
 

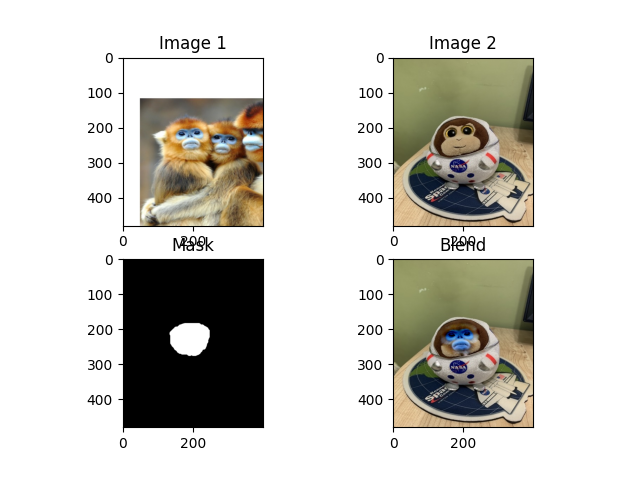


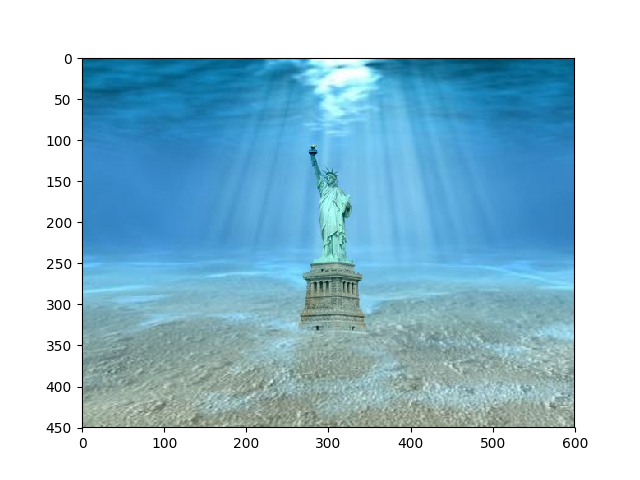
# Part B

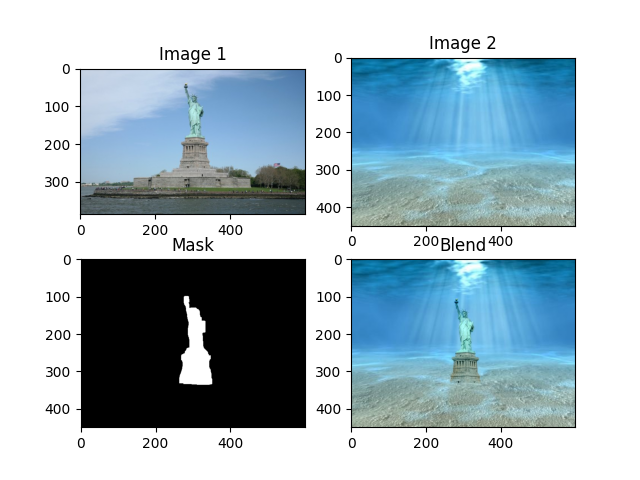
As for this part, I’ve followed the revert section in the “Convolution Pyramids” paper and built in the implementation a Shepard’s interpolation kernel.

Results:





Additional example:  




# Part C

In the time complexity analysis for both parts we can tell that the heaviest operation is the seamless cloning as all the other preparations are linear with N, the number of pixels in the biggest image of source, target and mask. Therefore, we can state that since Shepard's based convolution uses cv2.Filter2d which uses the frequency domain to apply the filter, therefore the time complexity of the blending is bound by O(N log N).  
However, in Possion based solver, it builds the blend by solving a sparse linear equation using multifrontal LU factorization which is bound by .

From profiling the execution on example 1 in each method I got On Macbook Pro mid-14, intel i5**:**Shepard's seamless cloning RGB: 100%|██████████| 3/3 [00:00<00:00, **8.56it/s**]  
Poisson seamless cloning RGB: 100%|██████████| 3/3 [03:36<00:00**, 72.16s/it**]

Where one iteration corresponds to one of the 3 RGB channel processing.

# Part D

I have implemented a simple GUI using open-cv interface API.

Usage:

python run\_clone.py [options]

Options:

-h Flag to specify a brief help message and exits.

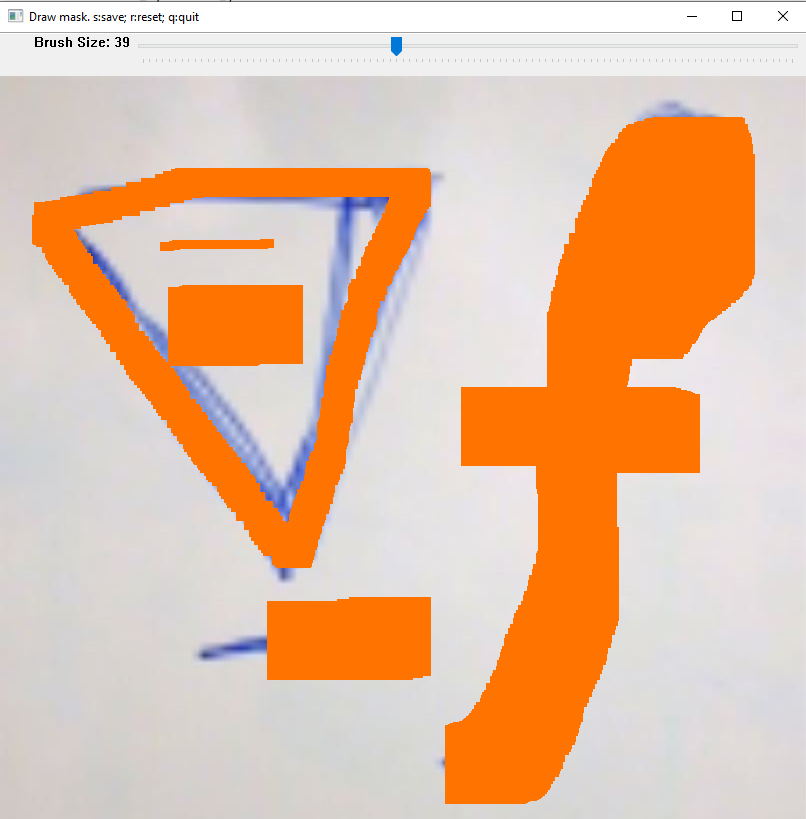
-s (Required) Specify a source image.

-t (Required) Specify a target image.

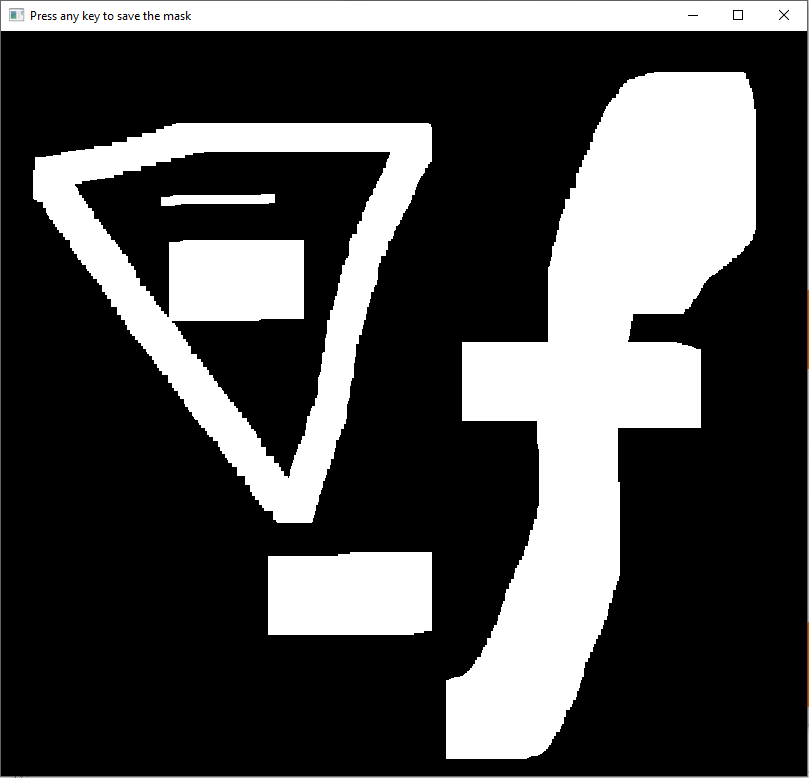
-m (Optional) Specify a mask image with the object in white and other part in black, ignore this option if you plan to draw it later.

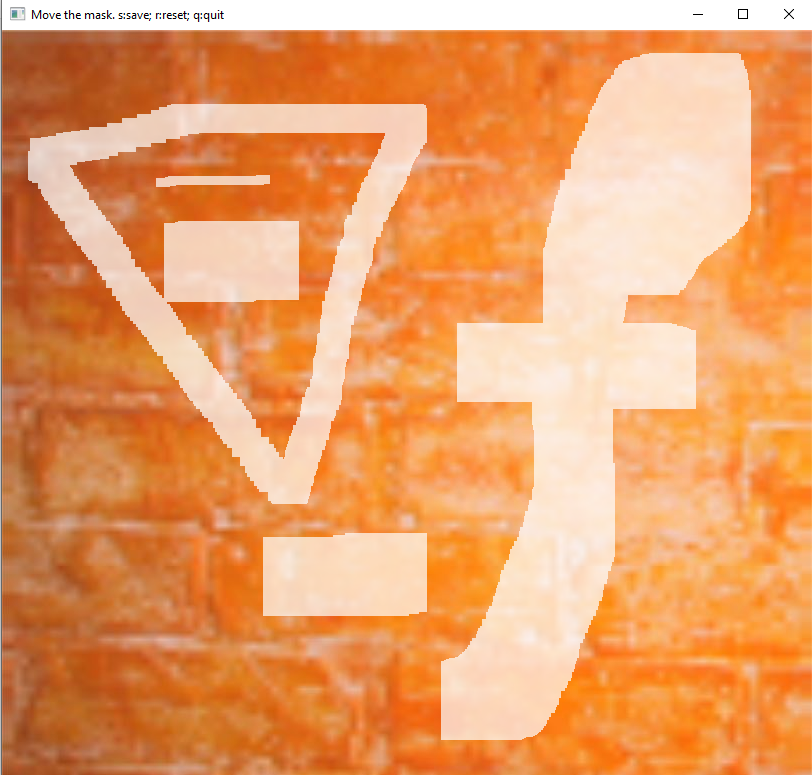
-x (Optional) Flag to specify a mode, either 'possion' or 'shepard'. default is possion.

In the mask painter, I’ve put a slider to enable controlling the brush size:



When finished and clicked ‘s’ for save, a new window will open to confirm and save drawn mask:



When saved, additional window will pop up to enable emplacing the mask on target image:  


And finally when saving the positioned mask, the selected cloning algorithm will operate on the images and output the result:

